

Estimating Burmese Python Abundance



1,4

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Project motivation

A need for demography estimates to study and evaluate control efforts

Traditional mark recapture programs not feasible or desirable

Detection probability extremely low

How can population size be estimated given current data streams?



Currently available data

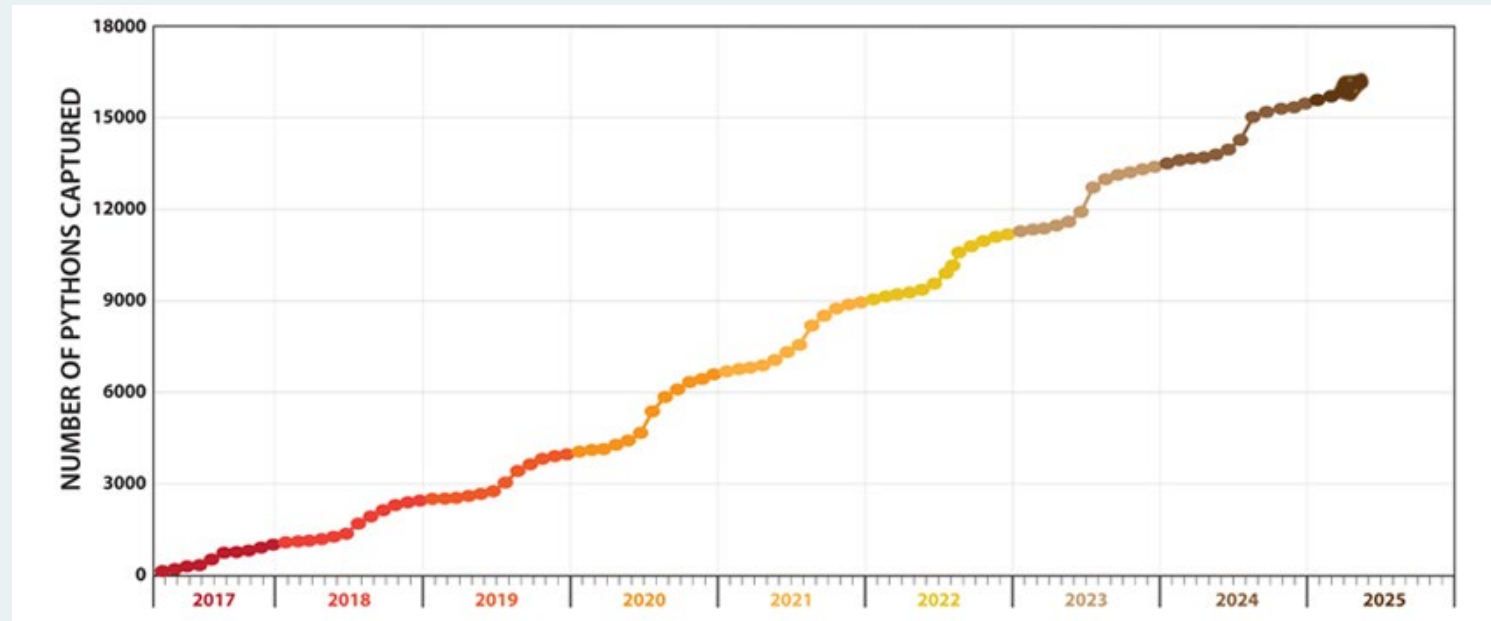
What data do we have?

Number of snakes removed from SFWMD and FWC removal program

What data do we need for a model?

Survey effort

Survey locations

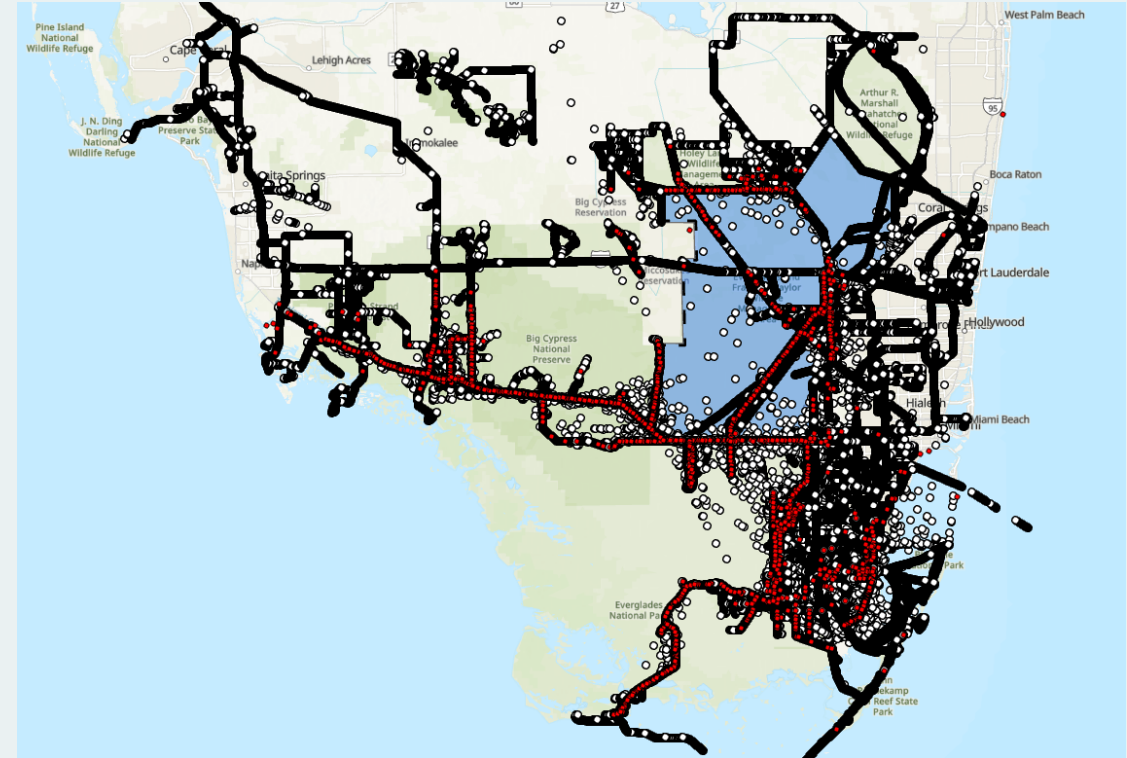


Currently available data

Contractor locations and effort

As of February 2021, ESRI's Survey123 app and 'MyTracks' feature used for contractor invoicing

Surveys must be linked to capture success and failure



An initial model

Starting simple

Starting with a specific site (EFST)*

Assuming population closure

No birth, death, or migration

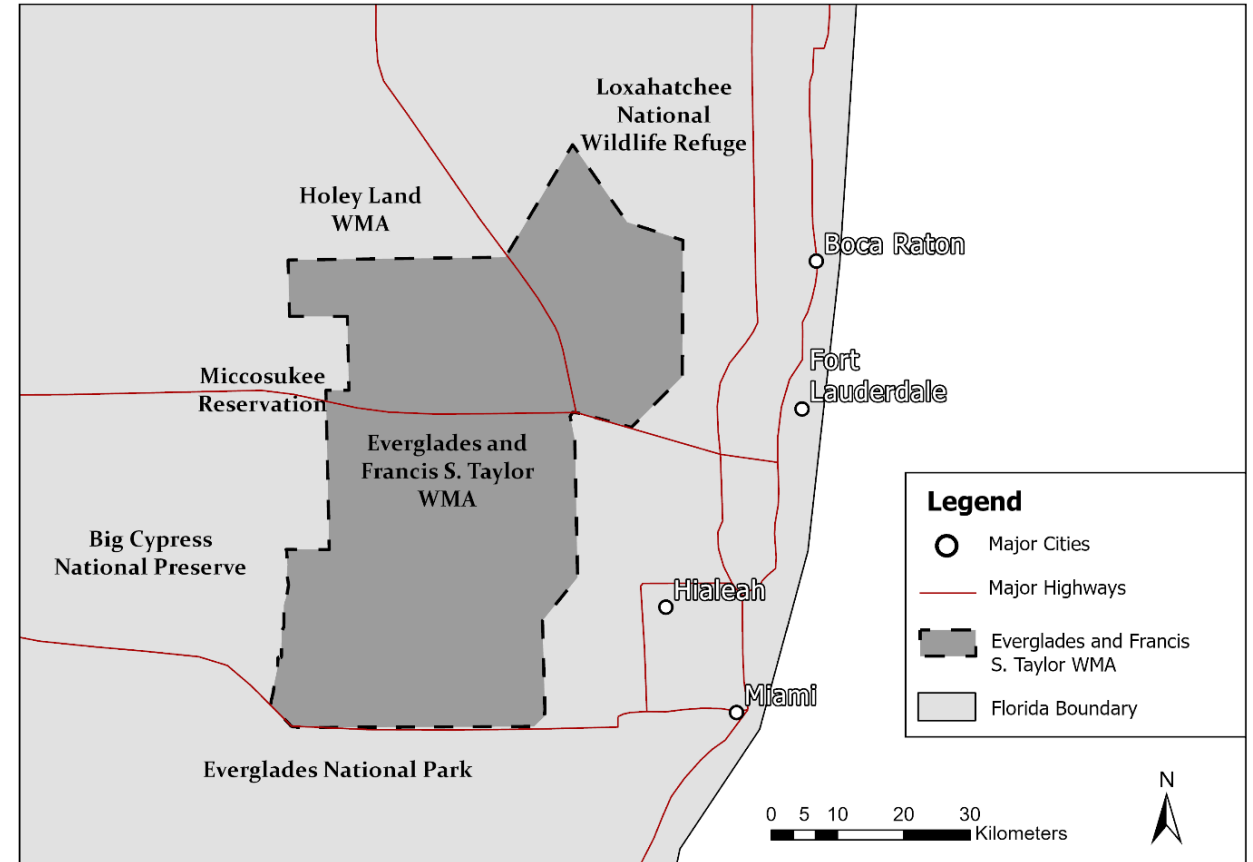
Short sampling period

Beginning with February 2021

Modeling framework

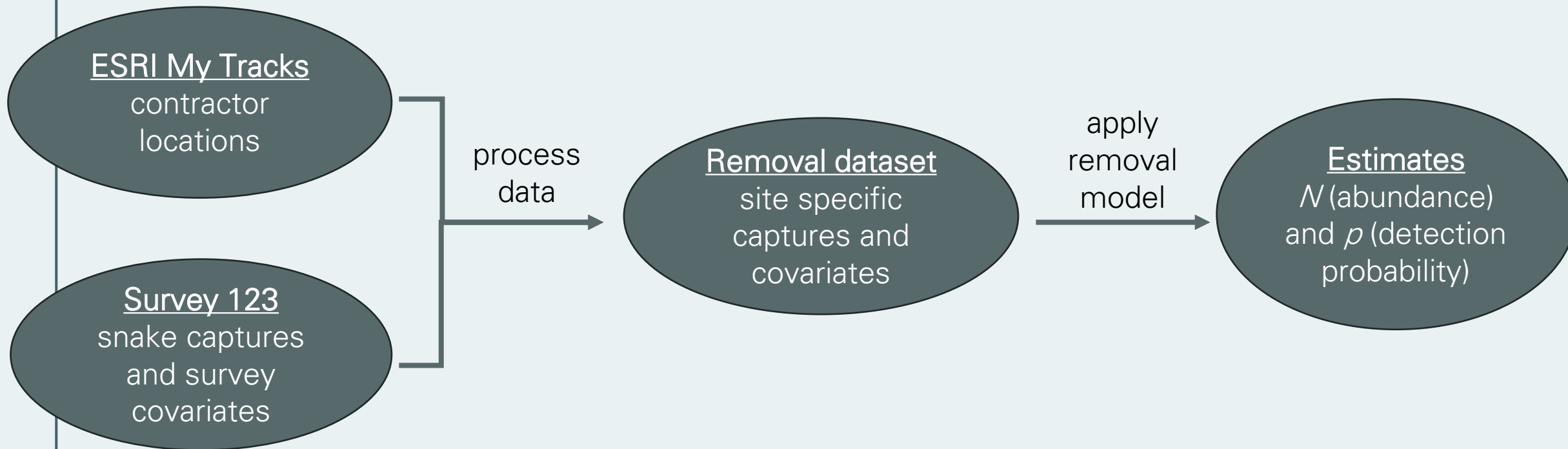
Removal model using N-mixture framework

Everglades and Francis S. Taylor WMA Study Site



*Brandon Welty
Linking Burmese Python Ecology with Removal Efforts in the Everglades
Session 42, 1:50pm

Analysis workflow



Processing data

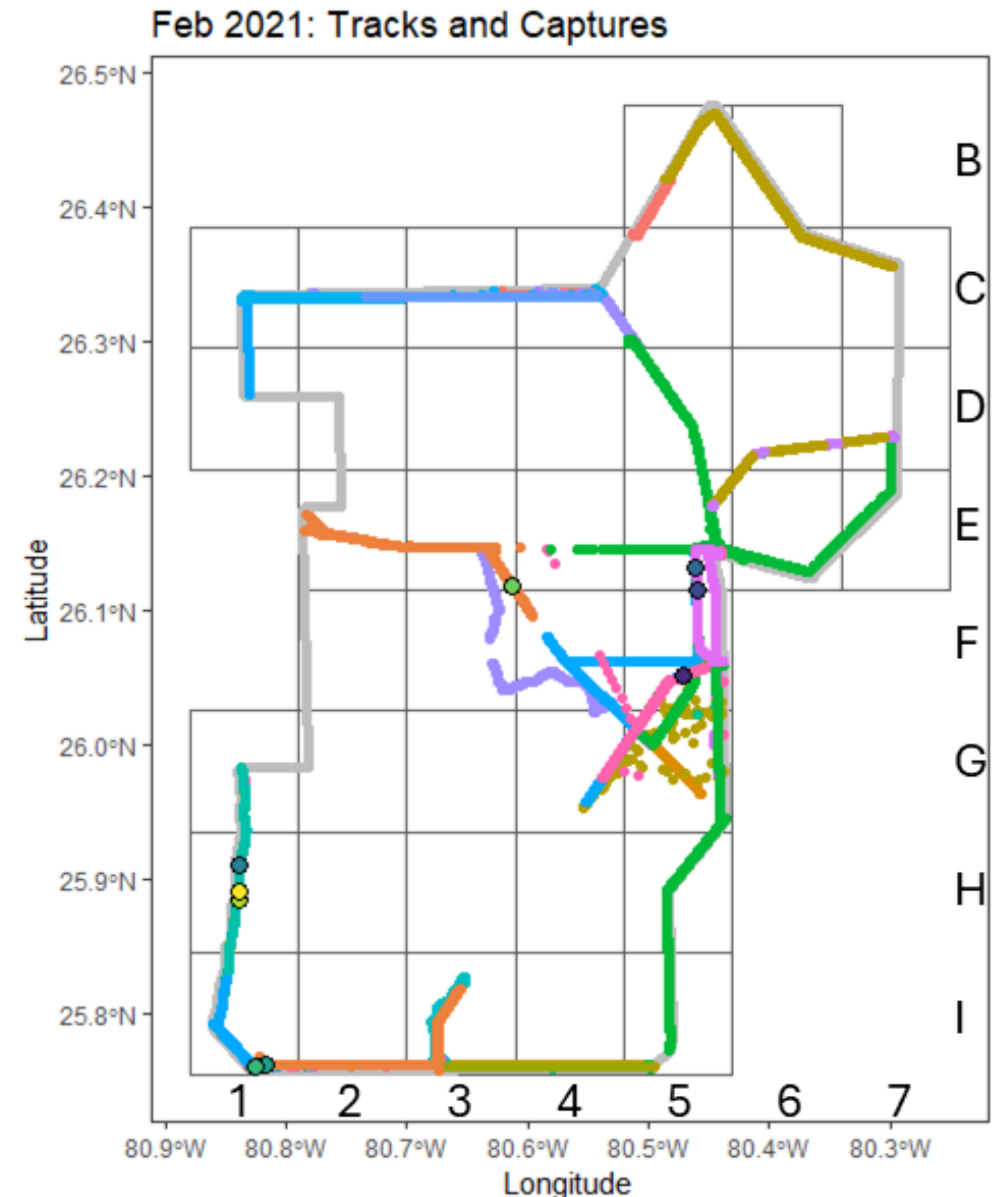
	site	date	effort_hours	captures	day
1	C2	2021-02-05	0.9958333	0	1
2	C3	2021-02-05	0.9041667	0	1
3	C4	2021-02-05	0.9602778	0	1
4	E5	2021-02-05	2.2980556	2	1
5	E6	2021-02-05	0.1844444	0	1

February 2021 data

30 sites with associated search effort,
searched for 1-17 days

Sites searched 0.5 – 2.5 hrs per site per day

10 python captures

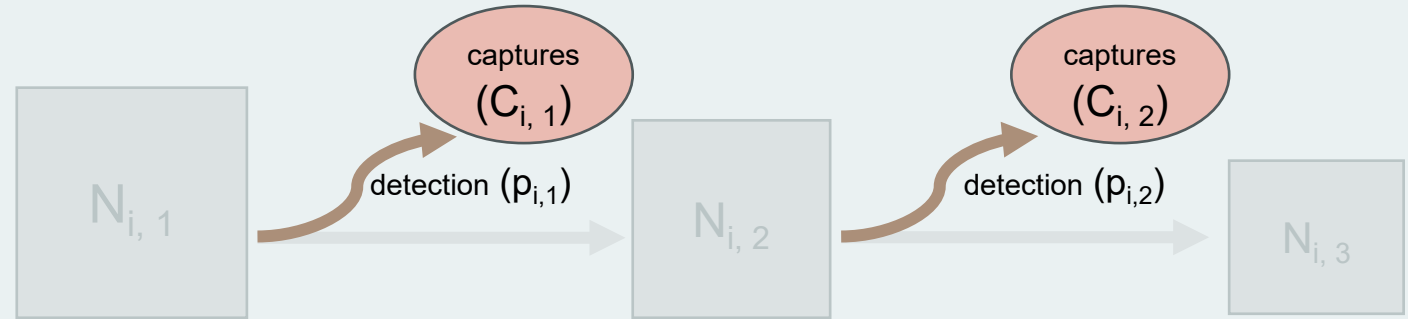


N-mixture removal model

Observation process:

$$C_{i,t} \sim \text{Binomial}(N_{i,t}, p_{i,t})$$

$$\text{logit}(p_{i,t}) = \beta_0 + \beta_1 \text{effort}_{i,t}$$



Underlying state process:

$$N_{i,t} \sim \text{Poisson}(\lambda) \text{ for } t = 1$$

$$N_{i,t} = N_{i,t-1} - C_{i,t} \text{ for } t \geq 2$$

Estimating λ , β_0 , and β_1

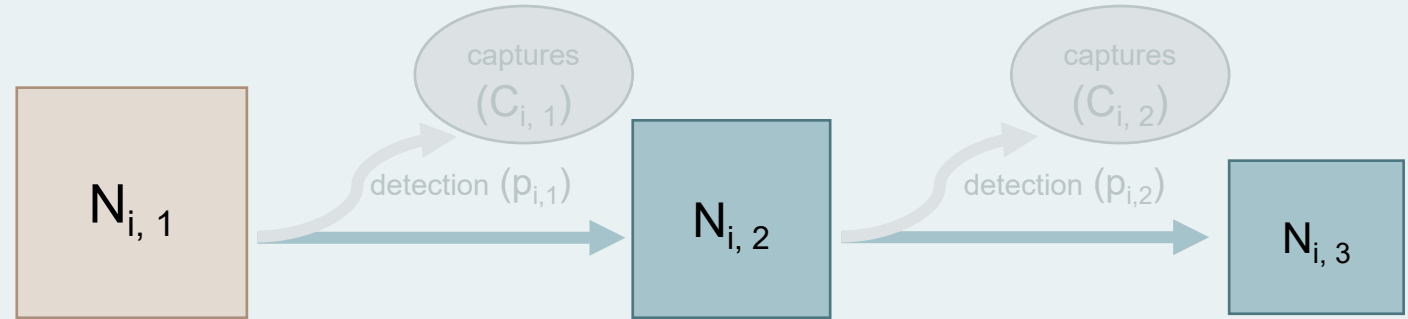
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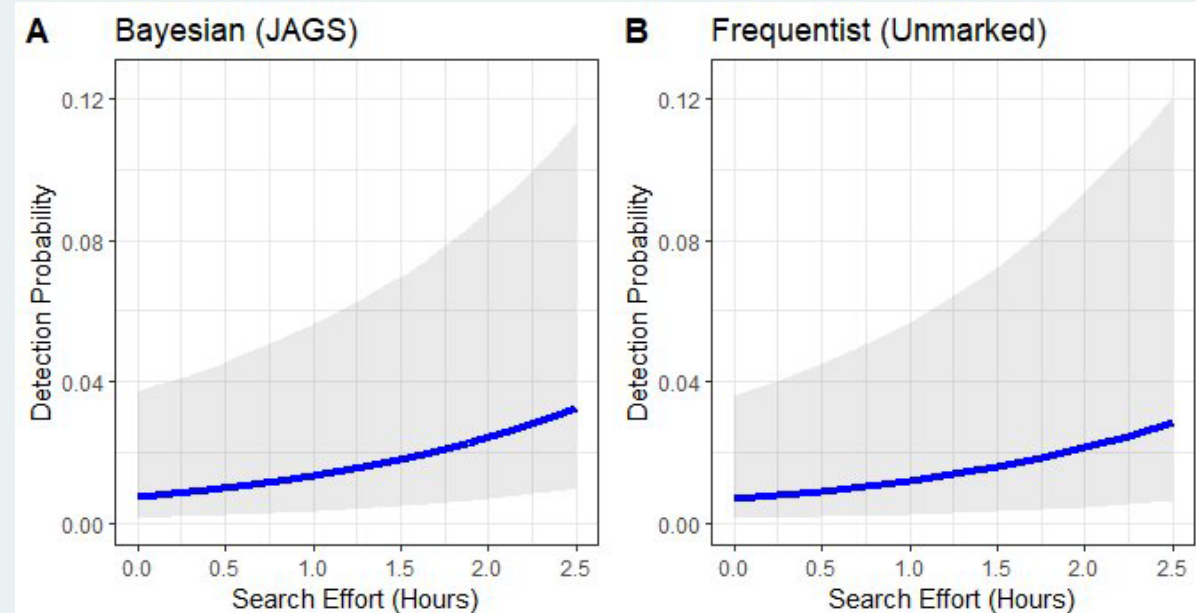
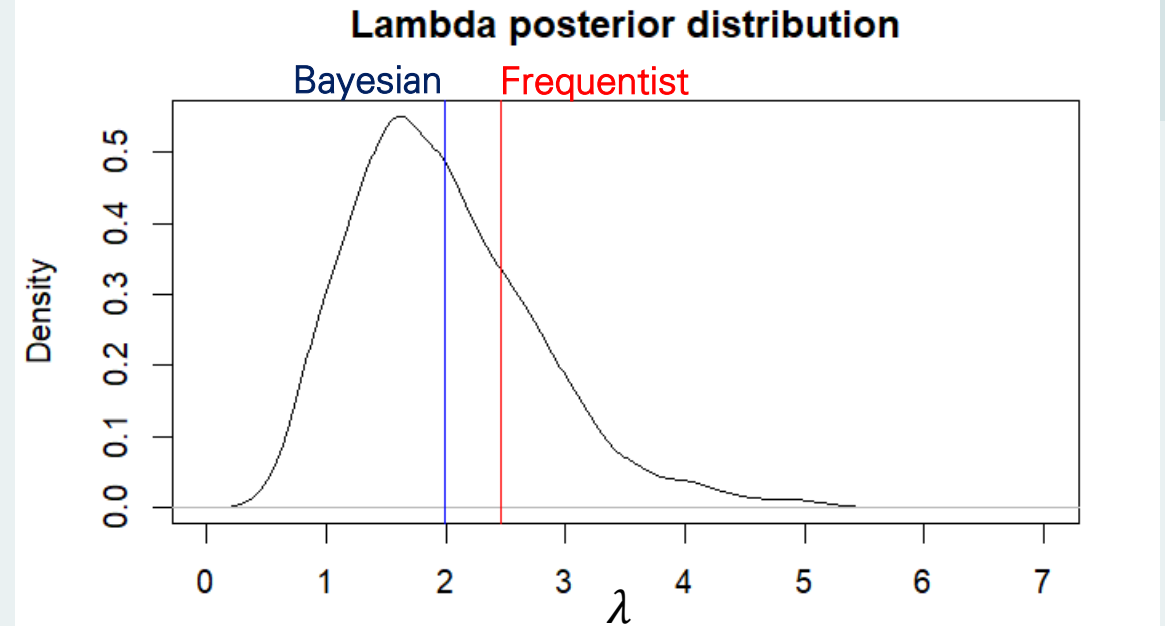
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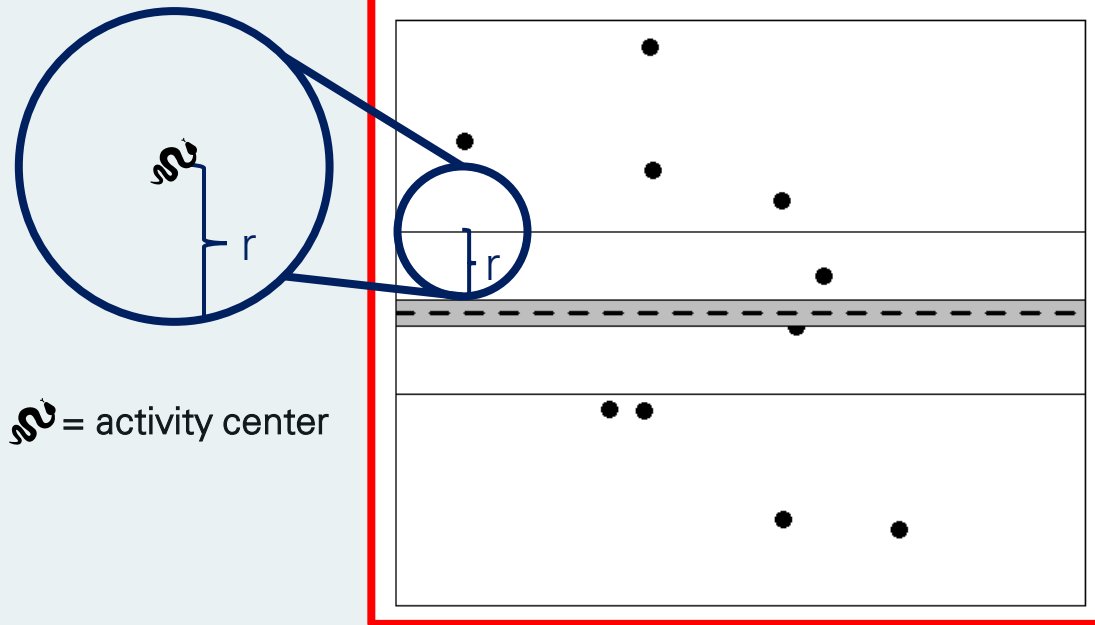
	site i	time t			
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N-mixture model results

Method	Parameter	Mean	LCI	UCI
Bayesian	λ	1.977	0.723	2.411
Frequentist	λ	2.46	0.806	7.528
Bayesian	β_0	-4.761	-6.259	-4.195
	β_1	0.594	0.319	0.690
	$p(1hr)$	0.015	0.004	0.064
Frequentist	β_0	-5.005	-6.719	-3.291
	β_1	0.589	0.292	0.887
	$p(1hr)$	0.012	0.002	0.057



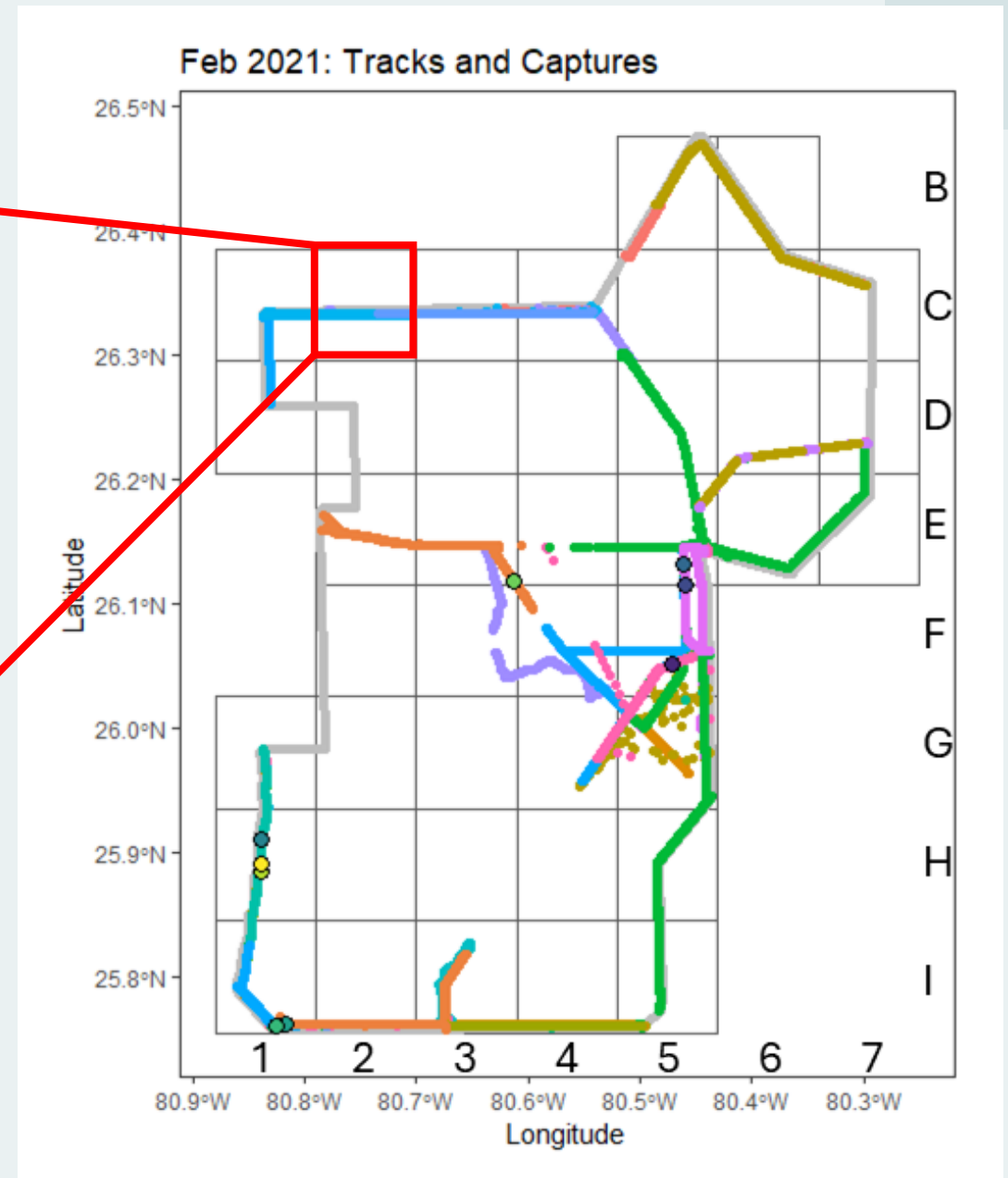
Interpreting results



Interpreting lambda

Approximately 2 pythons per 90 km²

$$\lambda = \text{Density} * \text{Effective Sampling Area}_i$$



Incorporating movement

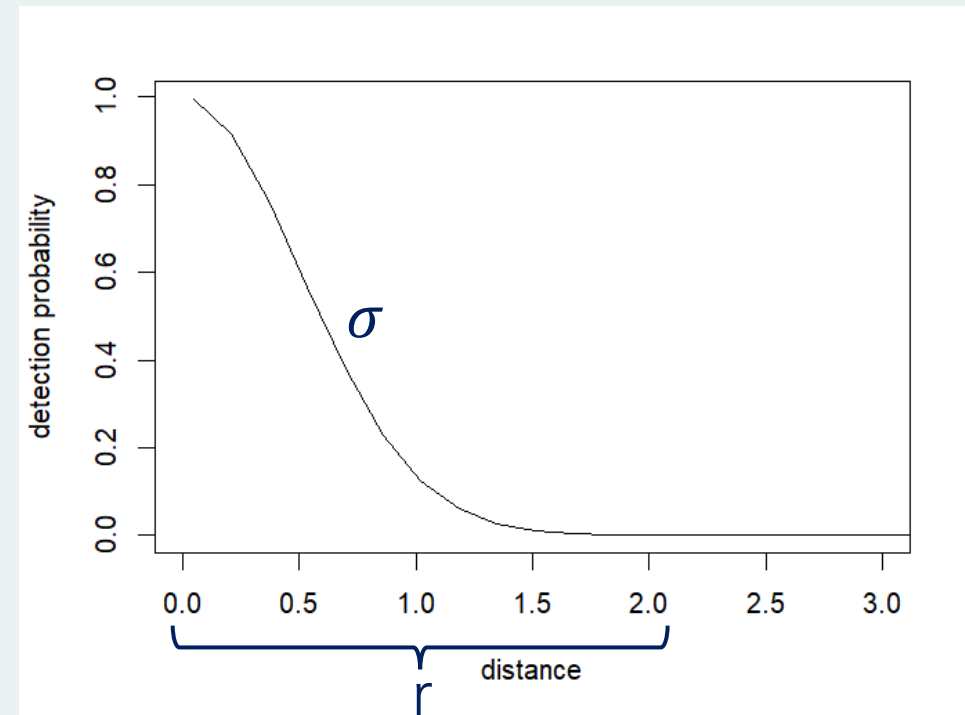
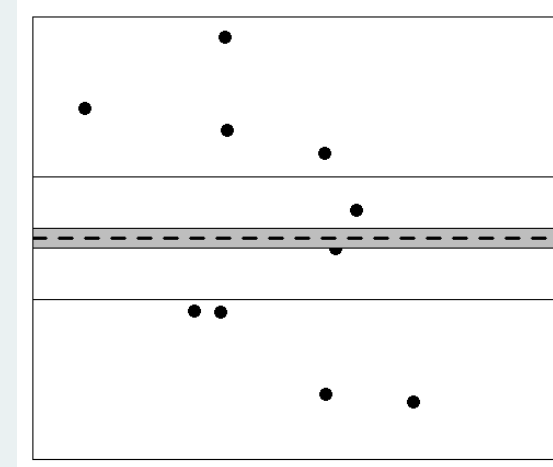
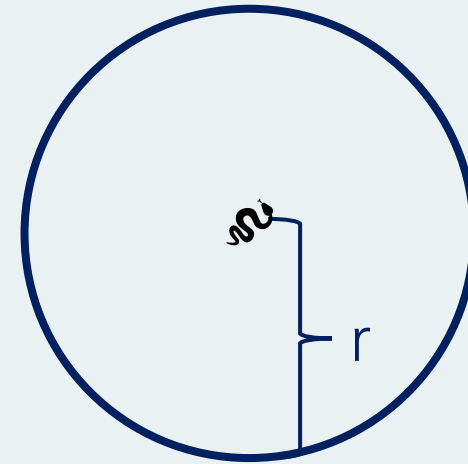
Distance sampling framework

$$p_i = p_0 \exp\left(-\frac{dist_i^2}{2\sigma^2}\right)$$

Typically, σ is estimated and distance is known

Potential solution

Using Data Augmentation to estimate number of activity centers



Testing through simulation

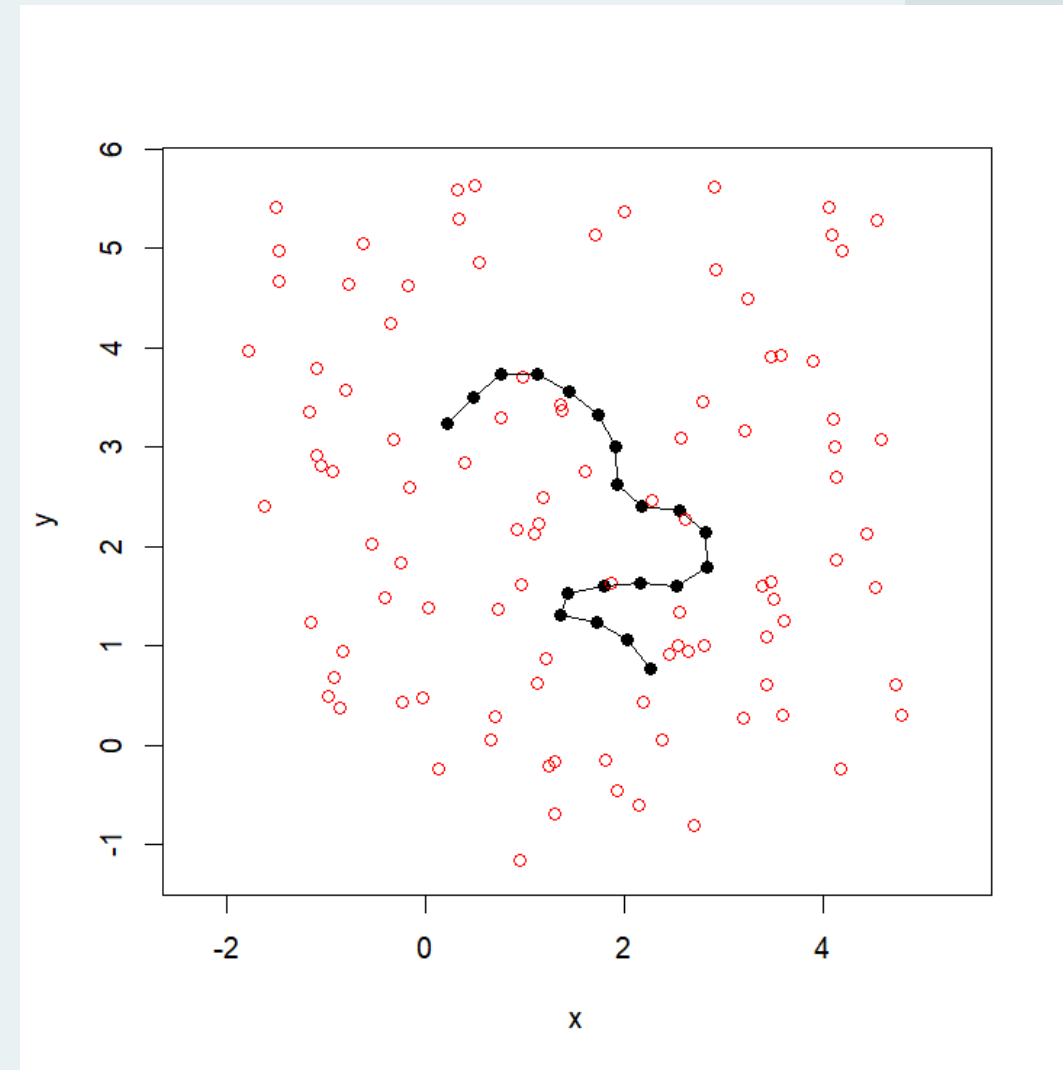
Simulated data

100 individuals

5 sampling occasions with removal

Transect divided into 20 potential capture locations

Estimate abundance with and without an informative σ prior



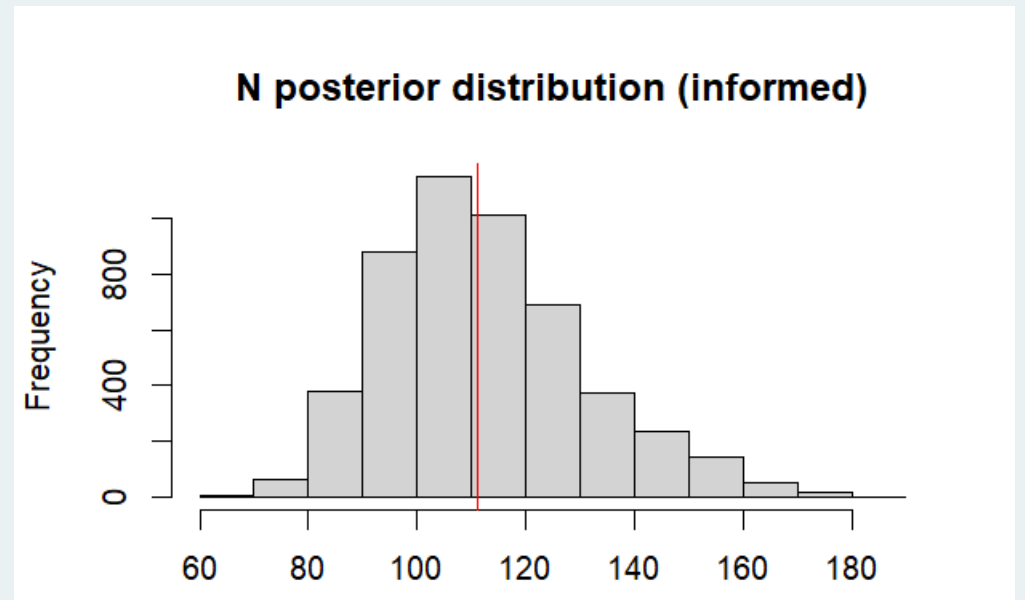
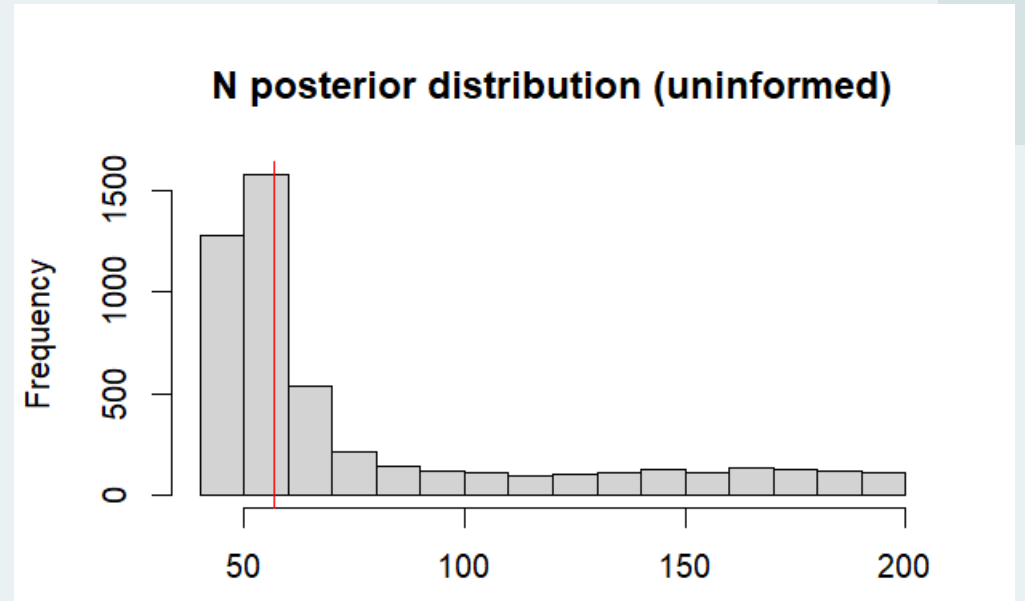
Testing through simulation

Results

Estimated abundance approaches truth when informative σ prior is used

Next steps

Incorporate true space-use ecology of pythons in EFST



Next steps

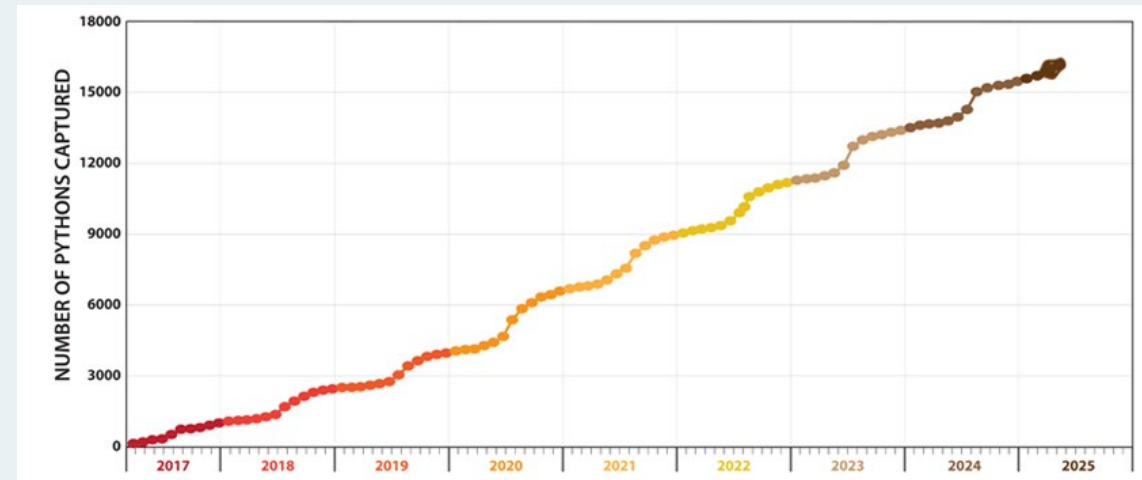
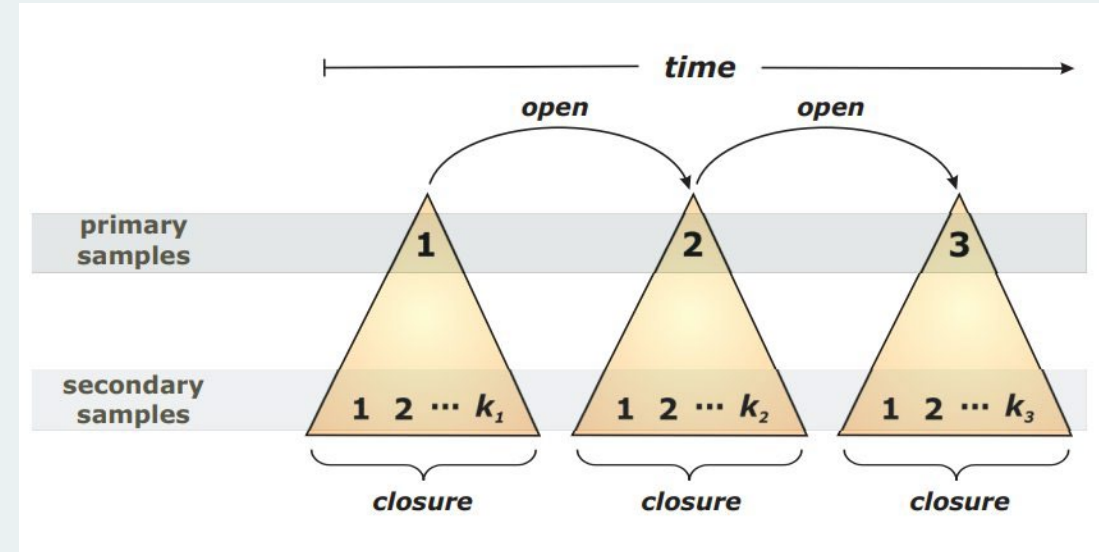
Additional covariates

Habitat covariates of density λ

Sex and breeding season covariates of movement σ

Multiple closed periods

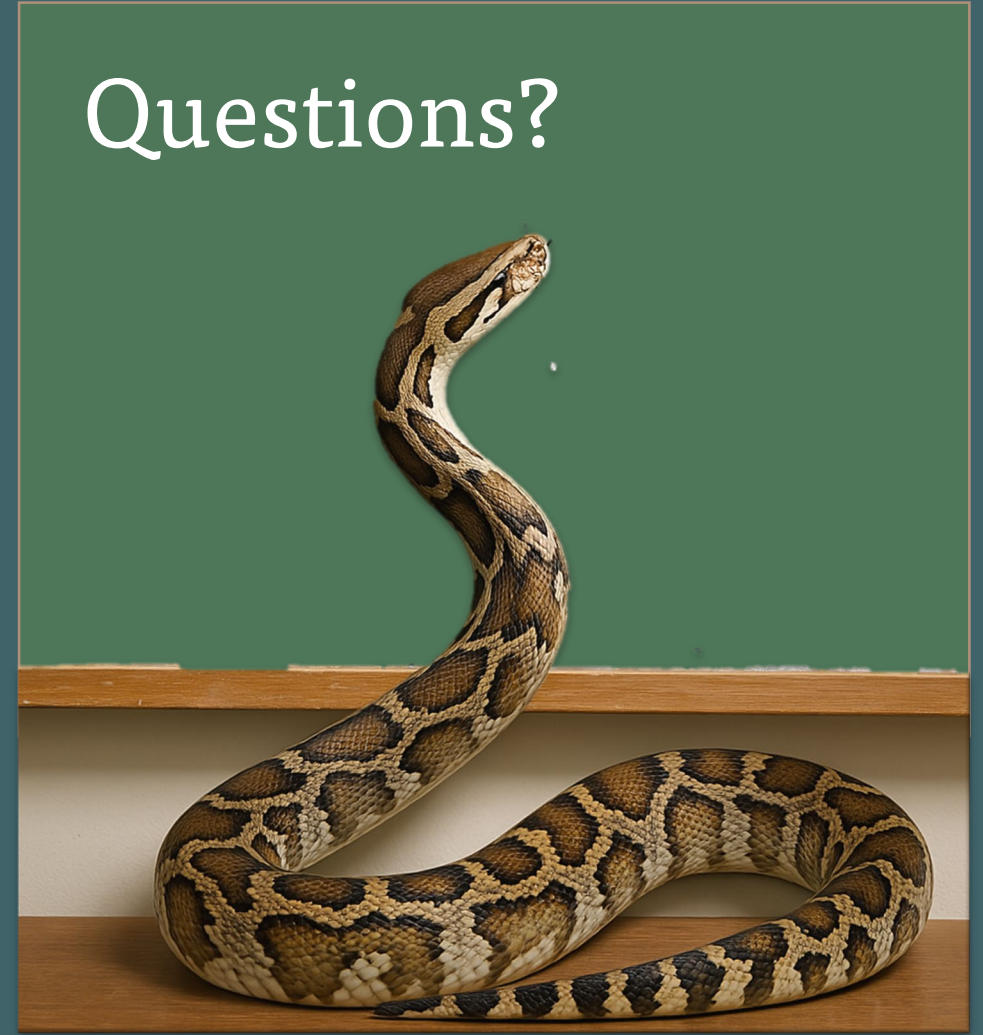
Expand model using 'Robust-Design' framework



Thank you!



Questions?



Data augmentation and distance

Data augmentation

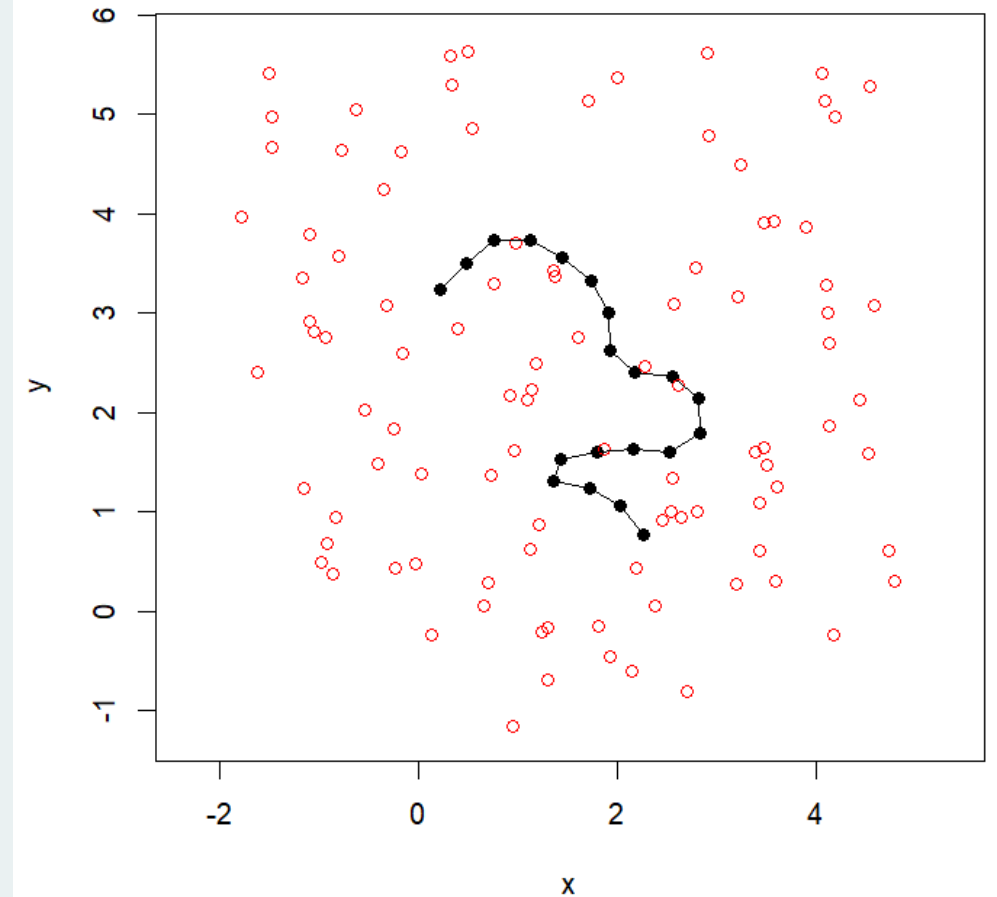
M = number of potential individuals

$$z_i \sim \text{Bernoulli}(\psi), \quad N = \sum_{i=1}^M z_i$$

Distance

$$p_{i,t} = p_0 \exp\left(-\frac{\text{dist}_{i,t}^2}{2\sigma_i^2}\right) * z_i$$

$$c_{i,t} \sim \text{Categorical}(p_{i,t})$$



Contents

Search

Drawing Order

Map

Feb21Captures

Feb21Tracks

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sites_89kmSq

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Feb21Tracks selection

allTracksEFST

downloadedTracks

sites_89kmSq

sites_7HalfKmsq

sites(7.5kmsq)

EFST_border

Map

1:20,633

80.4822047°W 26.1426421°N

allTracksEFST

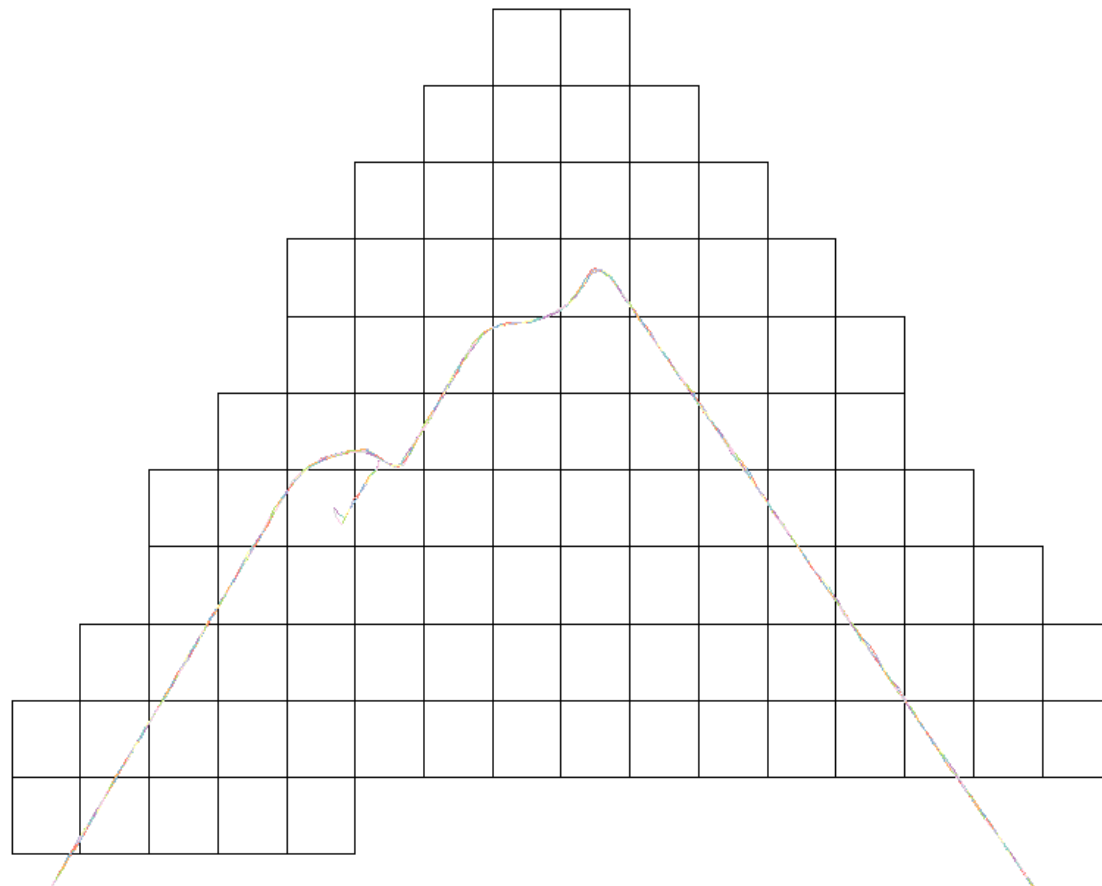
trackLines_Feb21

distGridEFST

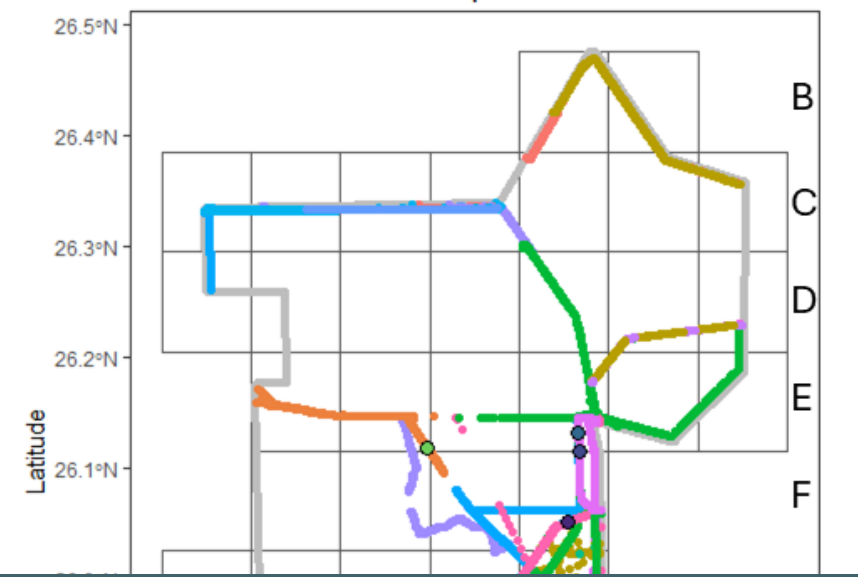
PEP_CapturePts

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2	6397	Polyline	0.000173	000fa6fa-ec0d-4da7-a...	0.000045	2.348603	dcrum_sfwmmd	dcrum_sfwmmd	2/4/2021 5:04:35 PM	2/4/2021 5:05:00 PM
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6	6401	Polyline	0.000278	000fa6fa-ec0d-4da7-a...	2.658501	3.153907	dcrum_sfwmmd	dcrum_sfwmmd	2/4/2021 5:05:12 PM	2/4/2021 5:05:21 PM



Feb 2021: Tracks and Captures



	V1	V2	V3	V4	V5
1	0.0000 [m]	223.7801 [m]	335.5276 [m]	250.0006 [m]	335.5276 [m]
2	223.7801 [m]	0.0000 [m]	512.6542 [m]	335.5276 [m]	250.0006 [m]
3	335.5276 [m]	512.6542 [m]	0.0000 [m]	223.7844 [m]	447.5689 [m]
4	250.0006 [m]	335.5276 [m]	223.7844 [m]	0.0000 [m]	223.7844 [m]
5	335.5276 [m]	250.0006 [m]	447.5689 [m]	223.7844 [m]	0.0000 [m]

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